

ECEF

[ECEF](#) [1] stands for Earth Centered Earth Fixed. It is a common frame of reference used by openSEA in both openINS and openCMD applications. A transform configuration provides the relationship of each sensor to the vehicle frame and openINS transforms the vehicle frame to [ECEF](#) [1].

Tags: [ecef](#) [2]

Source URL: <http://localhost:8888/kb2017/ecef-0>

Links

[1] <http://greenseainc.com/kb/lexicon/1#ecef>

[2] <http://localhost:8888/kb2017/tags/ecef>